

Code Driver: BLD60_I11

Code motor:BL400.48.120 + HREA48

Name parameters	Parameter description	Parameter range	Unit	Default value
P000	Control mode	40		40
P001	Pair of pole	0-255		04
P002	Rate speed	1-65535	RPM	3000
P003	Display mode	00: Speed motor 80: Current motor		00
P004	Starting torque	1-255		16
P005	Initial speed w/o sensor torque	1-255		04
P006	Acceleration time	0-255	0.1s	0
P007	Deceleration time	0-255	0.1s	0
P008	Current setting	1-255		14
P009	Temperature alarm setting	1-255		34
P010	Panel speed control		RPM	2000
P011	Brake force	0-1023		1023
P012	Site address	0-250		1
P013	Reserved			
P014	Current adjusting parameter	0-FF		3A
P015 to P031	ND	ND	ND	ND